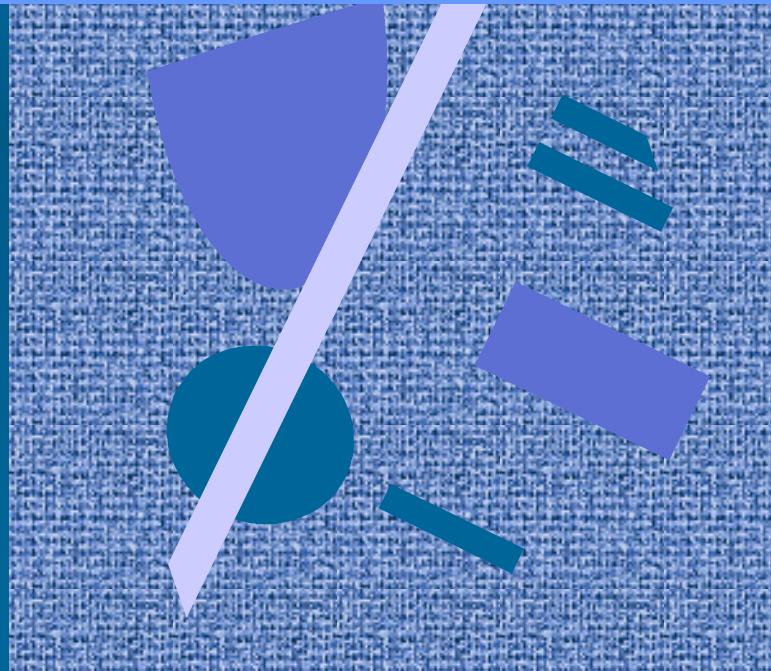


Cache

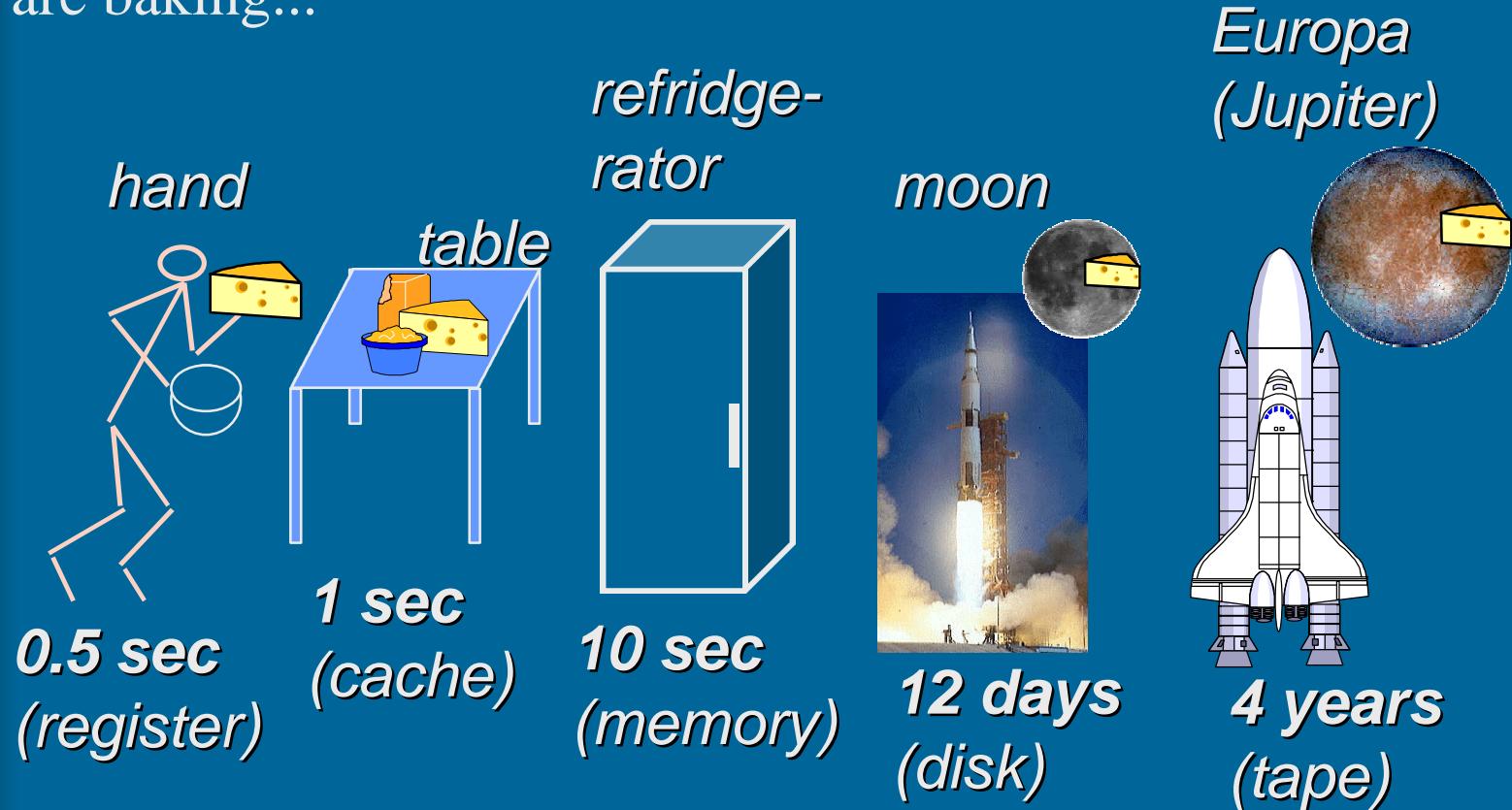
Ch 4.1-3

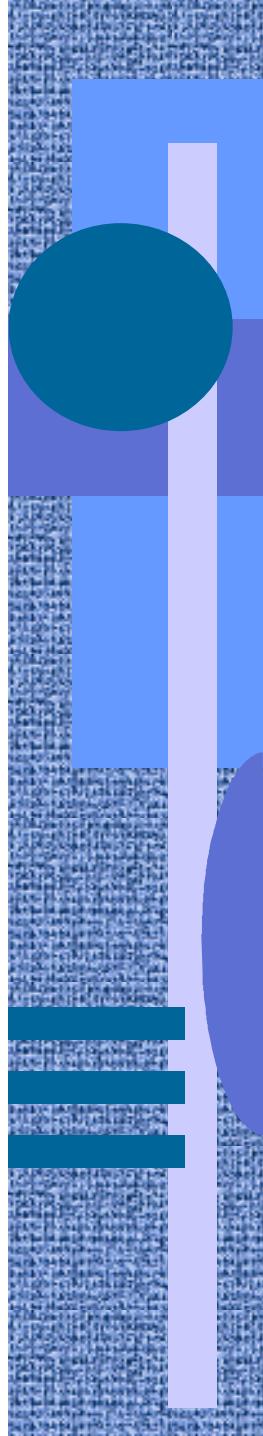


Memory Hierarchy
Main Memory
Cache
Implementation

HW Speed Parallel

Register, on-chip cache, memory, disk, and tape speeds relative to times locating cheese for the cheese cake you are baking...





Goal (4)

- I want my memory lightning fast
- I want my memory to be gigantic in size

- Register access viewpoint:

- data access as fast as from HW register
 - data size as large as memory

cache

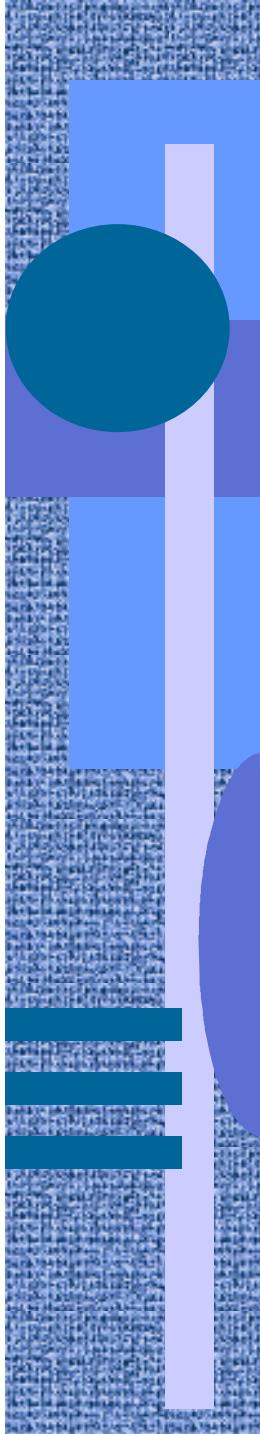
HW solution

- Memory access viewpoint

- data access as fast as from memory
 - data size as large as disk

virtual
memory

HW help for
SW solution



Memory Hierarchy (5)

- Most often needed data is kept close
- Access to small data sets can be made fast
 - simpler circuits
- Faster is more expensive
- Large can be bigger and cheaper

Memory Hierarchy

up: smaller, faster, more expensive,
more frequent access

down: bigger, slower, less expensive,
less frequent access

Fig. 4.1

Locality (5)

(paikallisuus)

Temporal locality

data referenced again soon

(ajallinen paikallisuus)

Spatial locality

nearby data referenced soon

(alueellinen paikallisuus)

- The reason why memory hierarchies work

Prob (small data set) = 99%

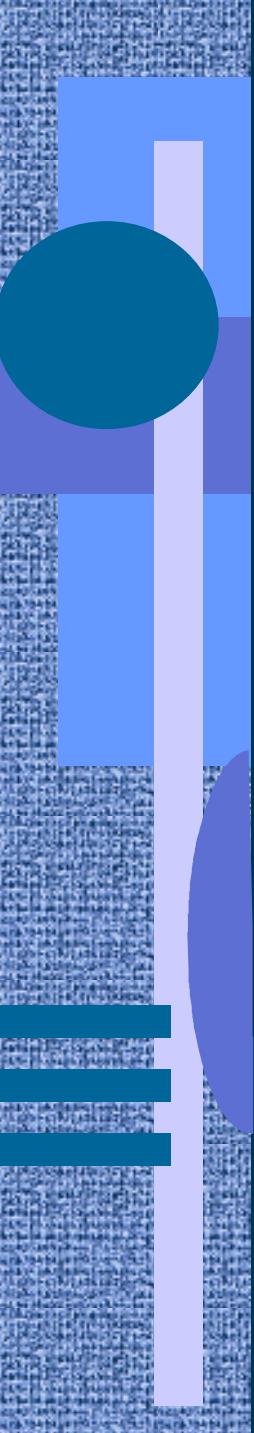
Prob (the rest) = 1%

Cost (small data set) = 2 μ s

Cost (the rest) = 20 μ s

$$\text{Aver cost } 99\% * 2 \mu\text{s} + 1\% * 20 \mu\text{s} = 2.2 \mu\text{s}$$

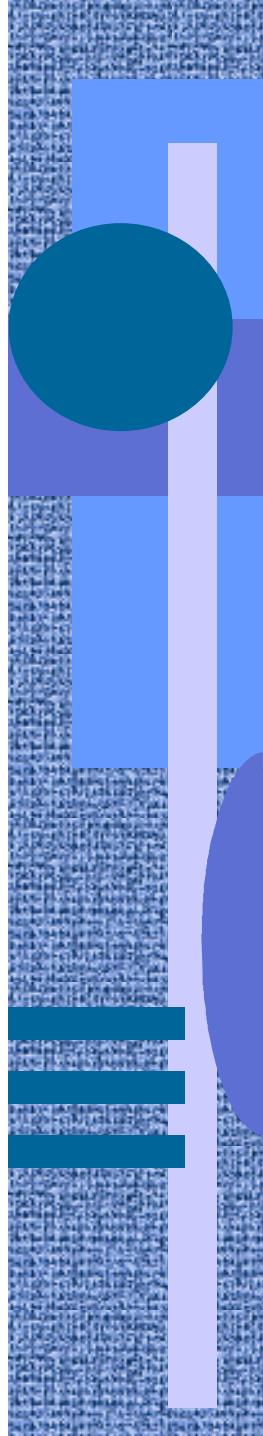
Close
to cost
of small
data set



Memory

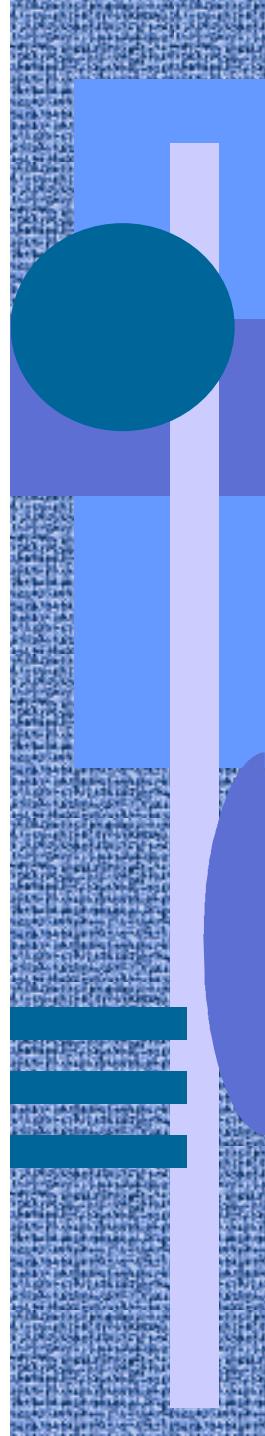
- Random access semiconductor memory
 - give address & control, read/write data
- ROM, PROMS
 - system startup memory,
BIOS (Basic Input/Output System)
 - load and execute OS at boot
 - also random access
- RAM
 - “normal” memory accessible by CPU

Table 4.2



RAM

- Dynamic RAM, DRAM \$5 / MB? (1997)
 - simpler, slower, denser, bigger (?)
 - main memory?
E.g., 60 ns access
 - periodic refreshing required
- Static RAM, SRAM \$100 / MB?
 - more complex, faster, smaller
E.g., 5 ns access?
 - cache?
 - no periodic refreshing needed
 - data remains until power is lost

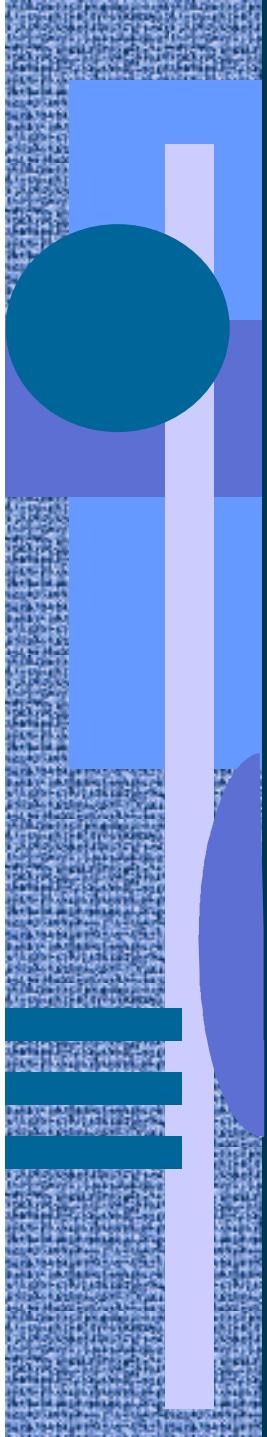


DRAM Access

- 16 Mb DRAM
 - 4 bit data items
 - 4M data elements, $2K * 2K$ square
 - Address 22 bits
 - row access select (RAS)
 - column access select CAS
 - interleaved on 11 address pins
- Simultaneous access to many 16Mb memory chips to access larger data items
 - Access 32 bit words in parallel? Need 8 chips.

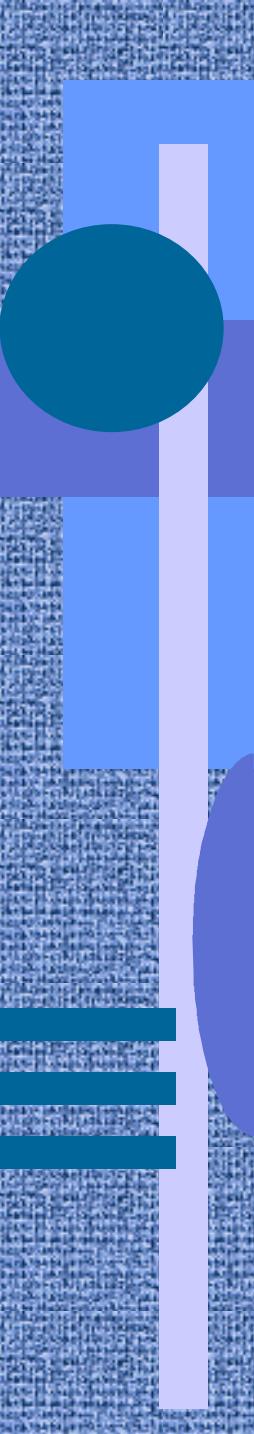
Fig. 4.4

Fig. 4.5 (b)



2.11.1999

Copyright Teemu Kerola 1999



Cache Memory

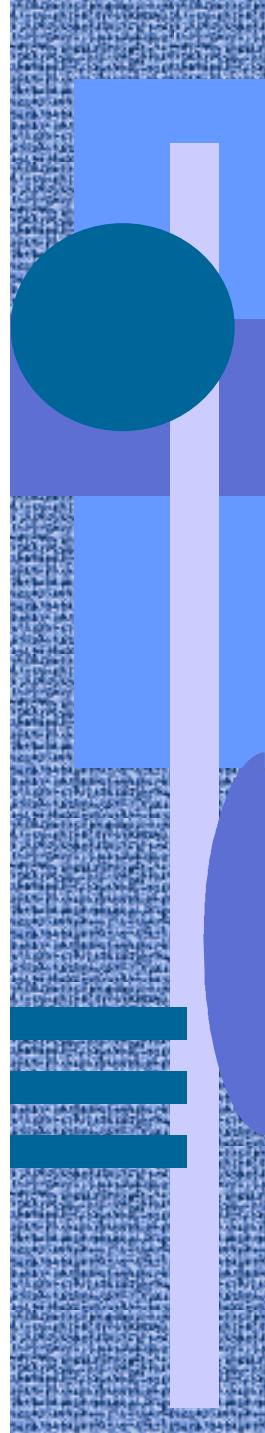
(välimuisti)

- Problem: how can I make my (main) memory as fast as my registers?
- Answer: (processor) cache
 - keep most probably referenced data in fast cache close to processor, and rest of it in memory
 - much smaller than main memory
 - (much) more expensive (per byte) than memory
 - most of data accesses to cache

90% 99% ?

Fig. 4.13

Fig. 4.16



Cache Operation (5)

- Data is in cache?

Hit

Data is only in memory?

Miss

Read it to cache

CPU waits until data available

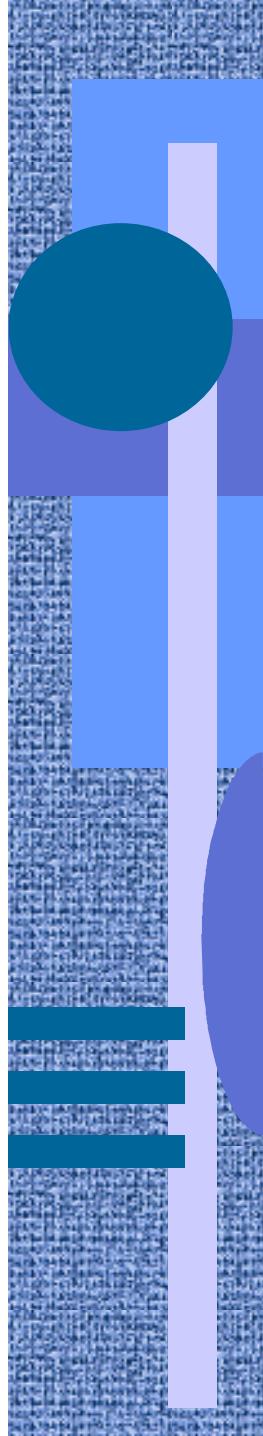
Fig. 4.15

Many blocks help for temporal locality
many different data items in cache

Fig. 4.14

Large blocks help for spatial locality
lots of “nearby” data available

Fixed cache size?
Select “many” or “large”?



Cache Features

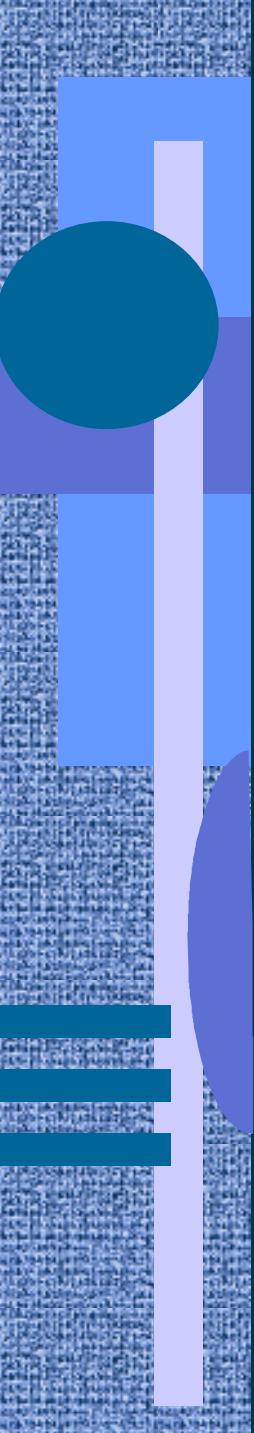
- Size
- Mapping function
 - how to find data in cache?
- Replacement algorithm
 - which block to remove to make room for a new block?
- Write policy
 - how to handle writes?
- Line size (block size)?
- Number of caches?

(kuvausfunktio)

(poistoalgoritmi)

(kirjoituspolitiikka)

(rivin tai lohkon koko)



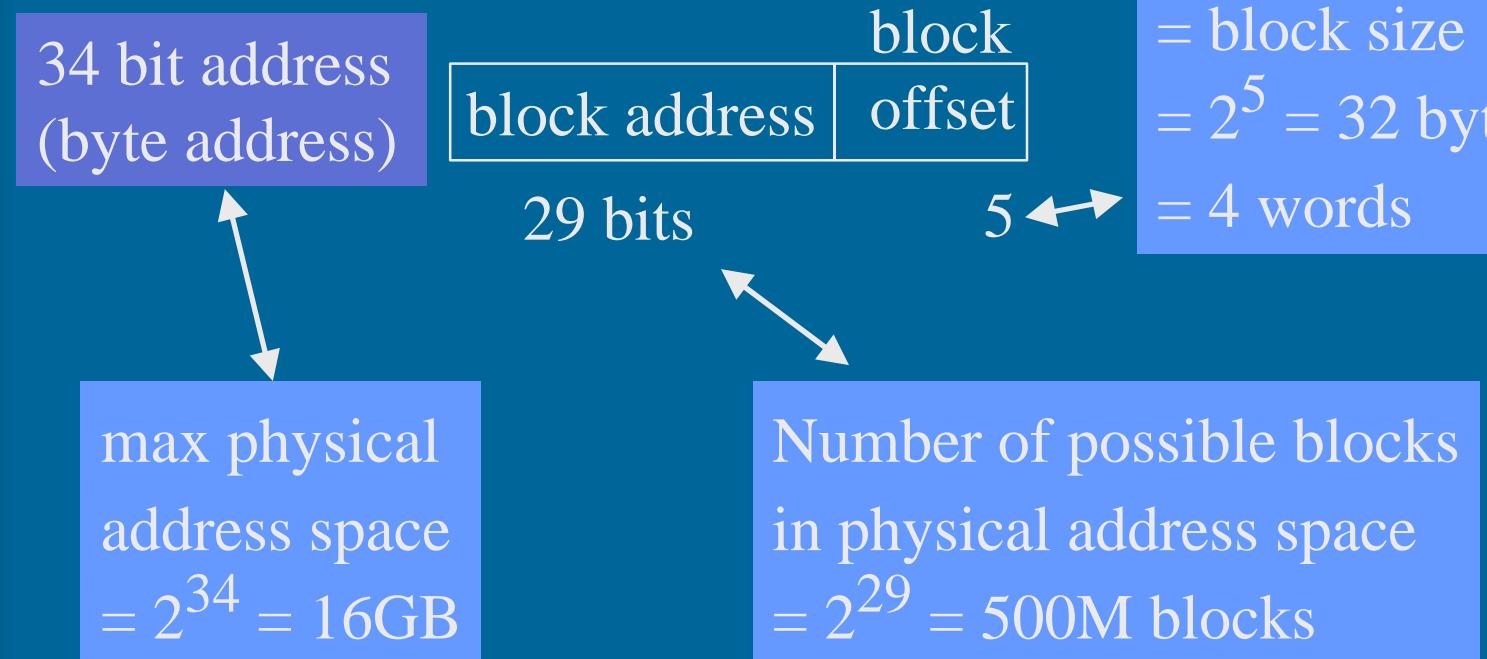
Cache Size

- Bigger is better in general
- Bigger may be slower
 - lots of gates, cumulative gate delay?
- Too big might be too slow!
 - Help: 2- or 3-level caches

1KW (4 KB), 512KW (2 MB)?

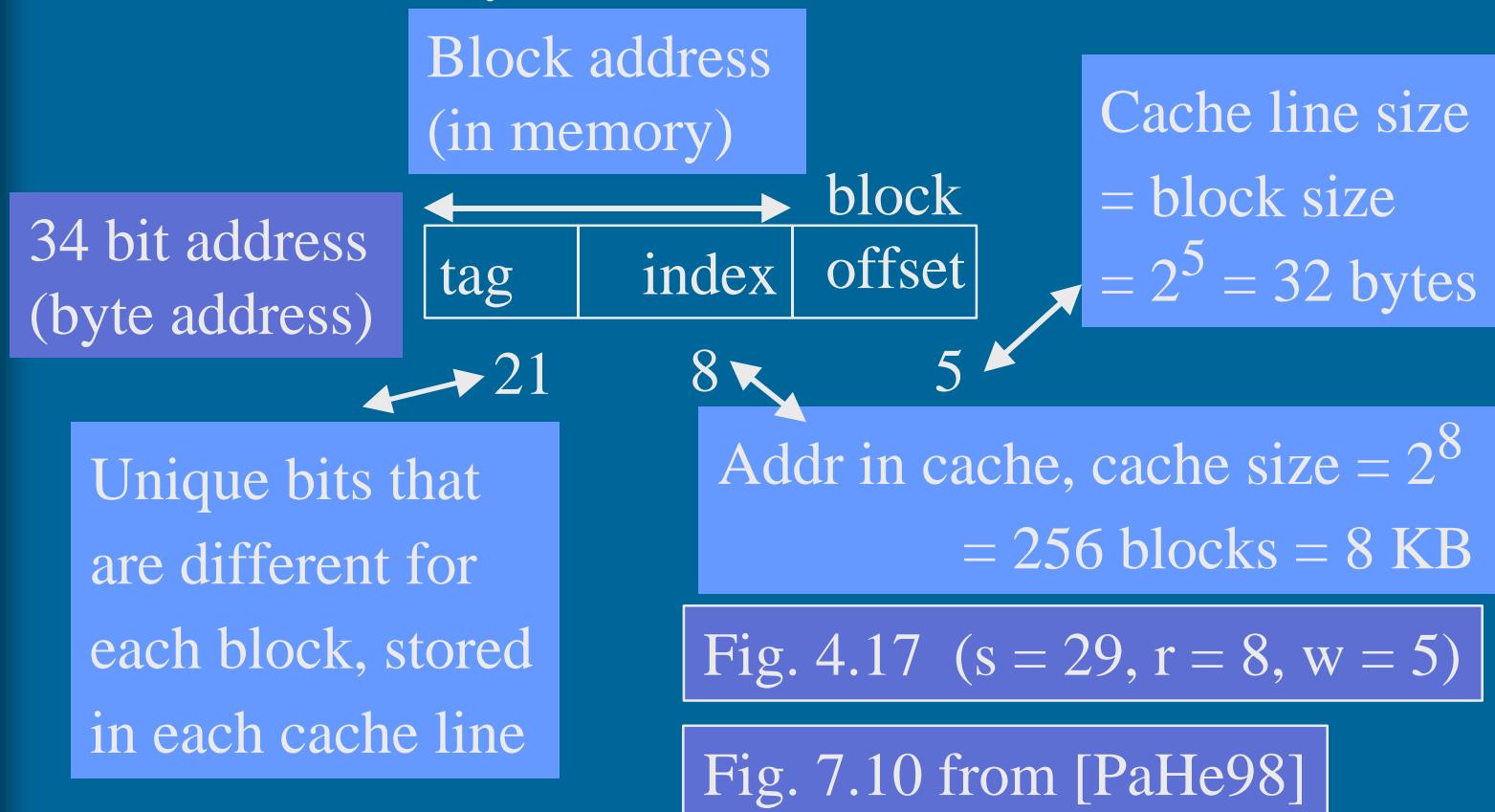
Mapping: Memory Address (3)

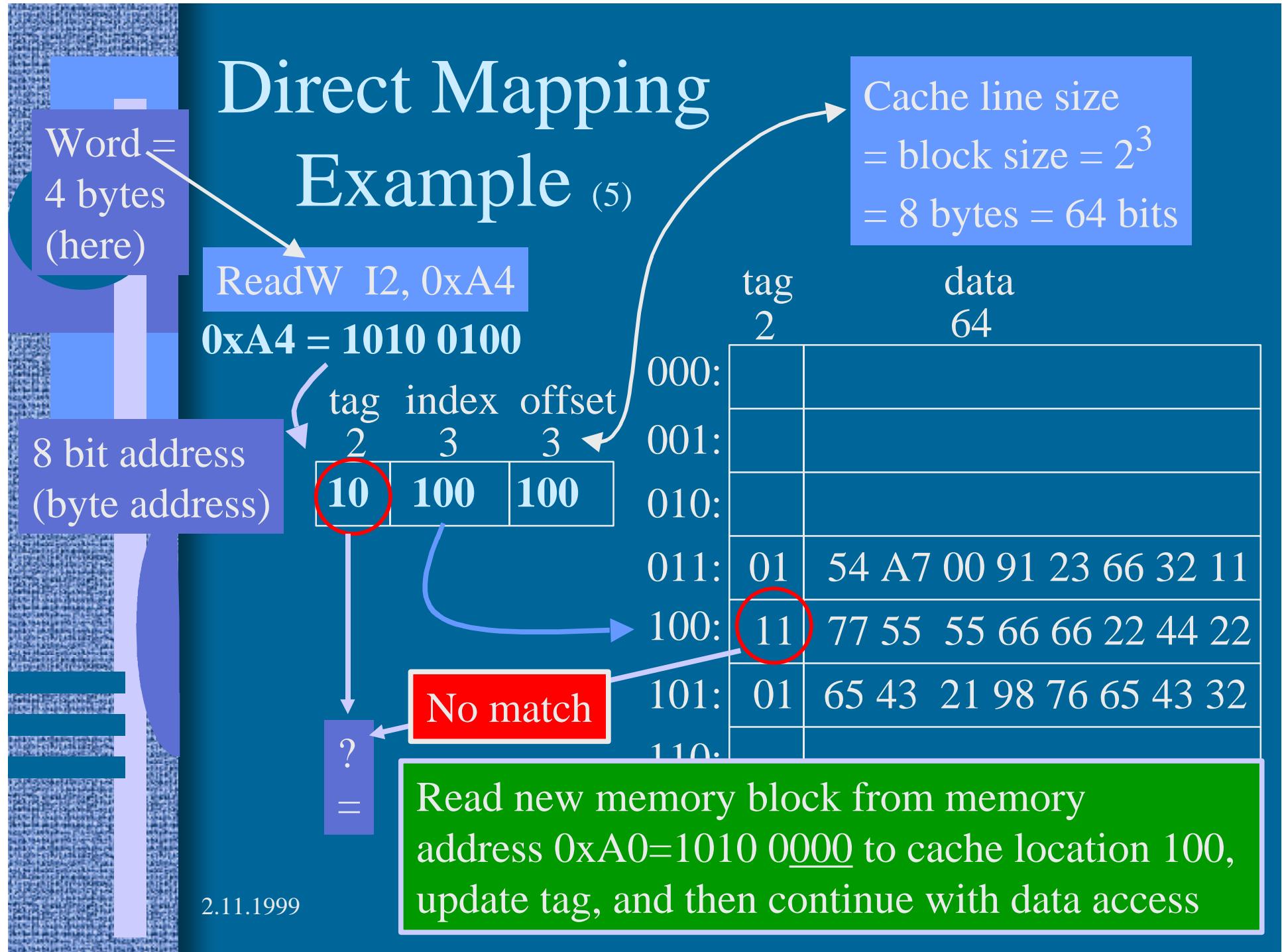
- Alpha AXP issues 34 bit memory addresses
 - At cache hit block offset is controlling a multiplexer to select right word



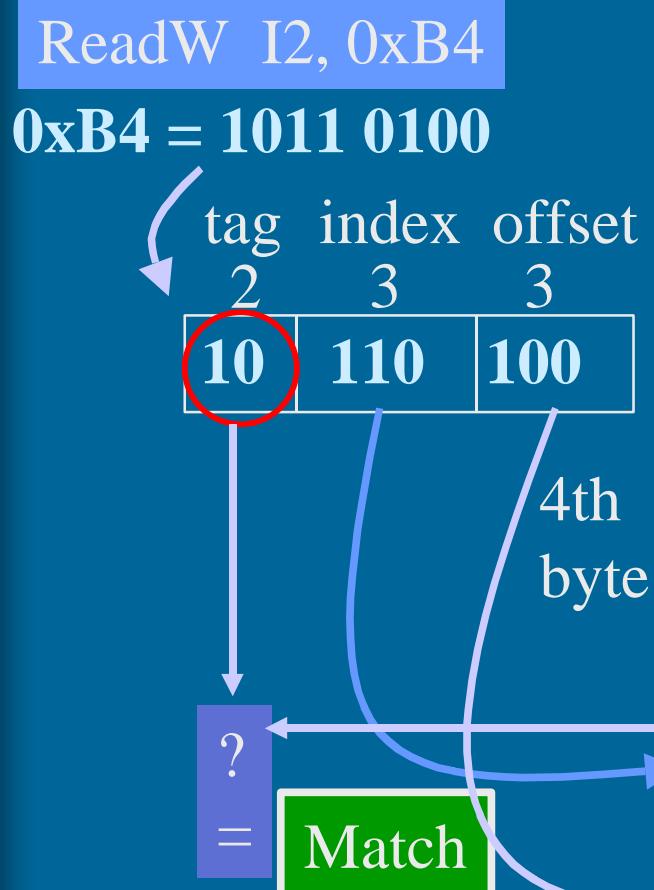
Direct Mapping (6)

- Every block has only one possible location (cache line number) in cache
 - determined by index field bits

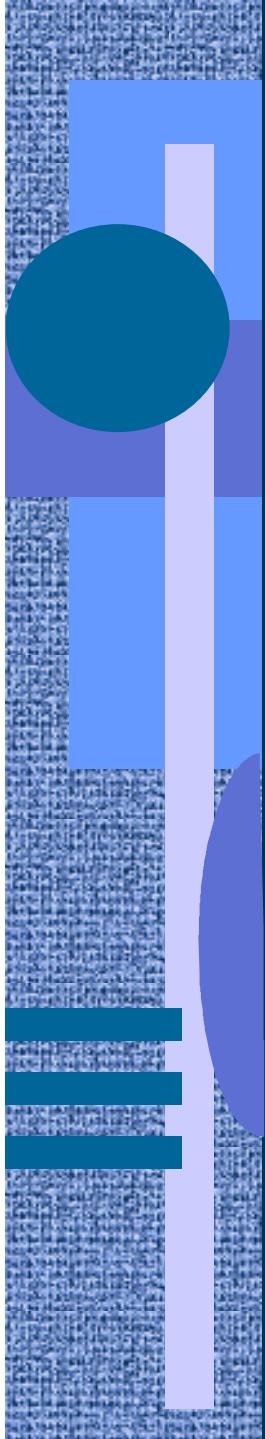




Direct Mapping Example 2 (5)



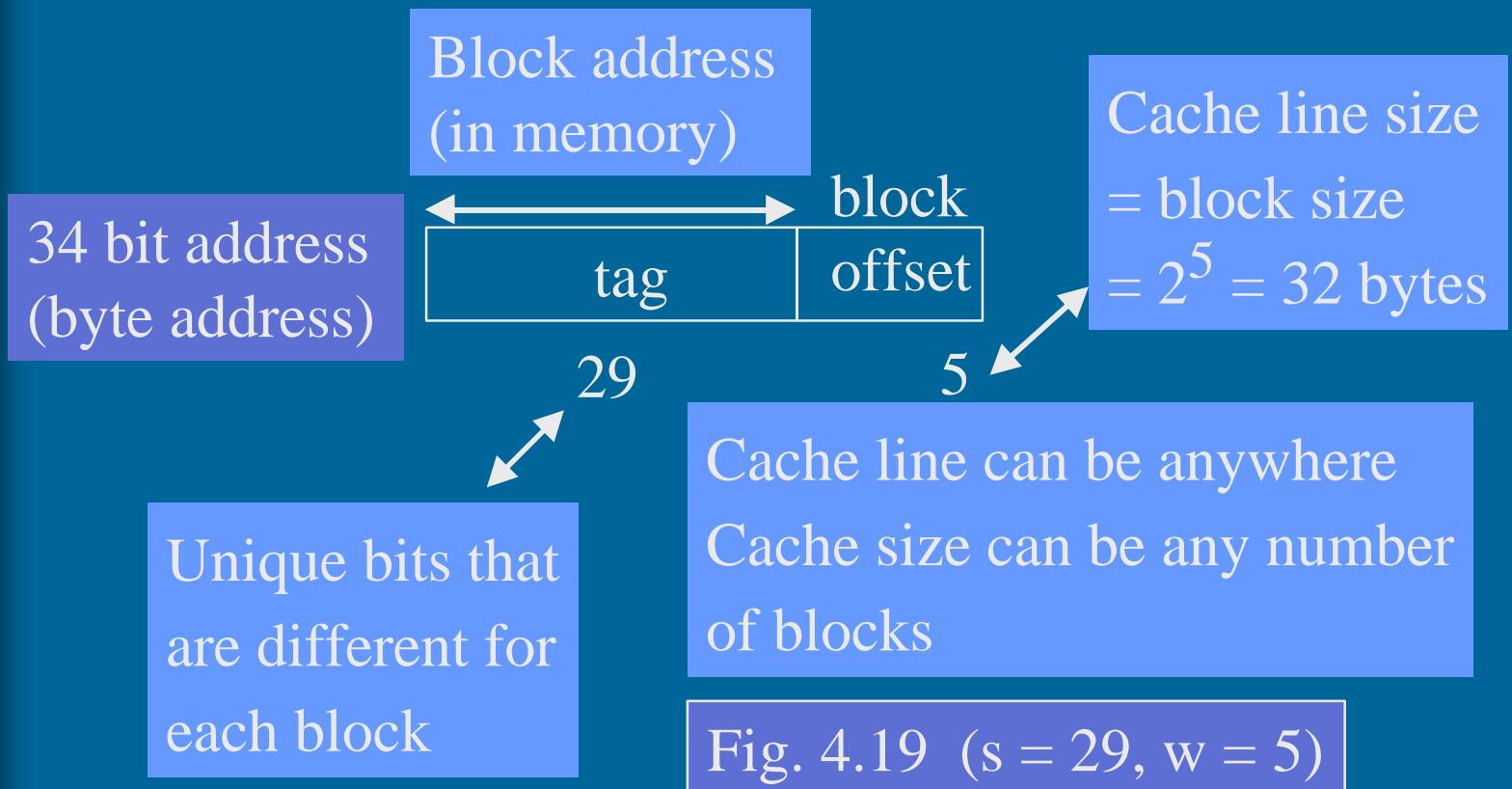
	tag	data
000:		64
001:		
010:		
011:	01	54 A7 00 91 23 66 32 11
100:	11	77 55 55 66 66 22 44 22
101:	01	65 43 21 98 76 65 43 32
110:	10	00 11 22 33 44 55 66 77
111:		

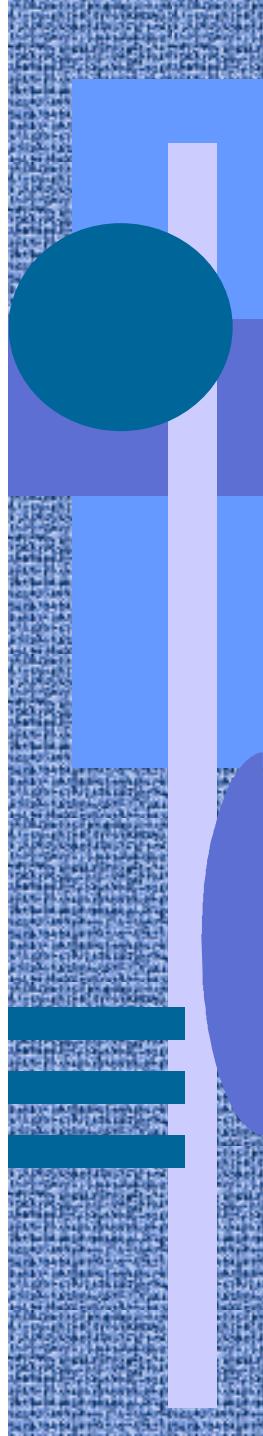


Fully Associative Mapping (5)

(täysin assosia-
tiivinen kuvaus)

- Every block can be in any cache line
 - tag must be complete block address



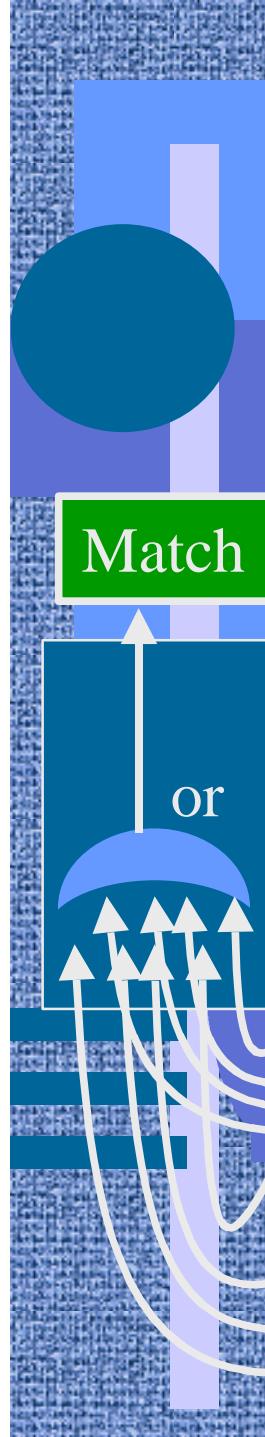


Fully Associative Mapping

- Lots of circuits
 - tag fields are long - wasted space!
 - each cache line tag must be compared simultaneously with the memory address tag
 - lots of wires
 - lots of comparison circuits
- Final comparison “or” has large gate delay
 - did any of these 64 comparisons match?
$$2 \log(64) = 8 \text{ levels of binary gates}$$
 - how about 262144 comparisons? 18 levels?
- \Rightarrow Can use it only for small caches

Large surface area on chip

Fully Associative Example (5)



ReadW I2, 0xB4

0xA4 = 1011 0100

tag 5 offset 3

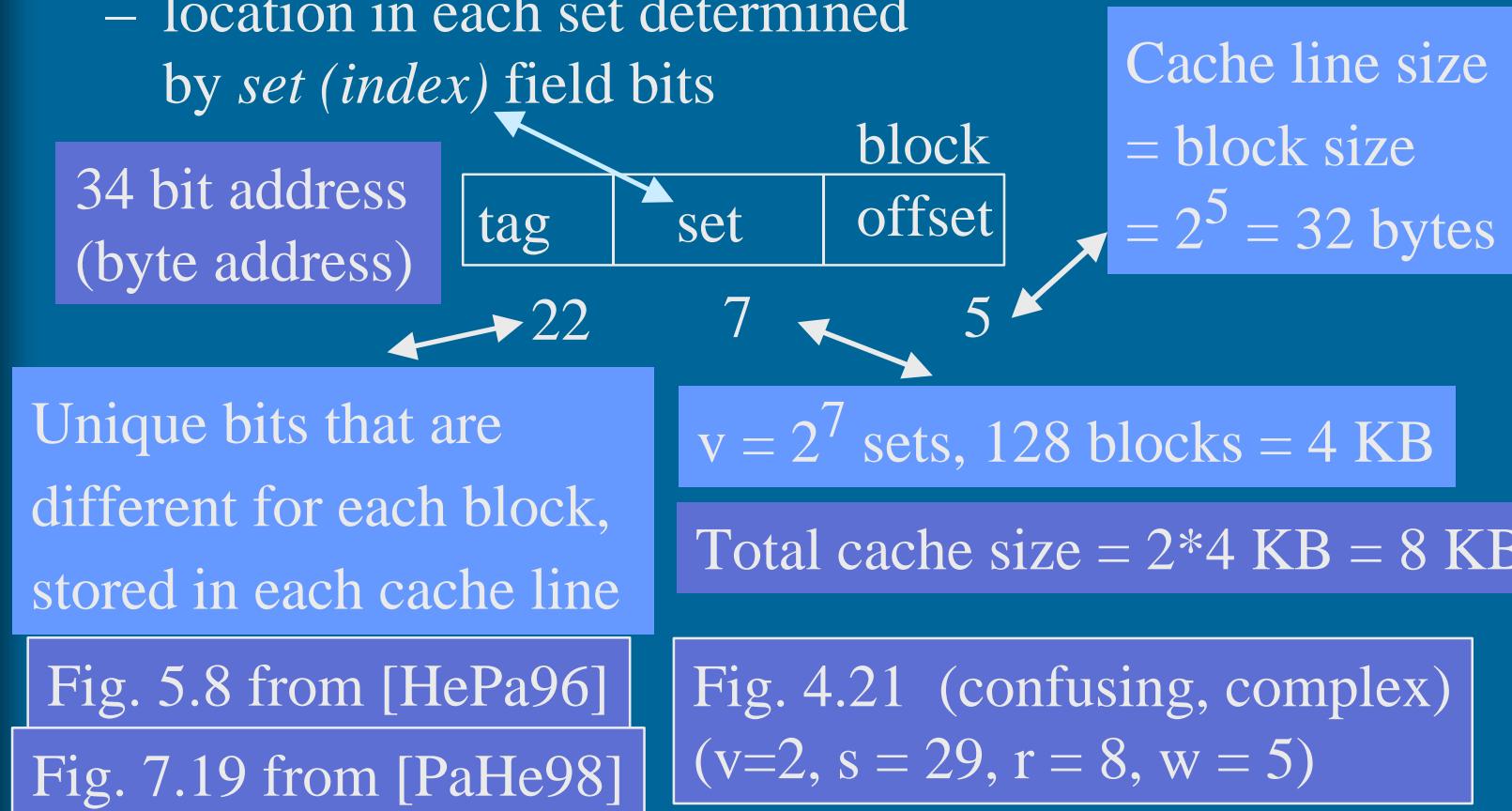
10110 | **100**

	tag 5	data 64
000:	11011	12 34 56 78 9A 01 23 45
001:	10111	87 00 32 89 65 A1 B2 00
010:	00011	87 54 00 89 65 A1 B2 00
011:	10100	54 A7 00 91 23 66 32 11
100:	00111	77 55 55 66 66 22 44 22
101:	10100	65 43 21 98 76 65 43 32
110:	10110	00 11 22 33 44 55 66 77
111:	10011	87 54 32 89 65 A1 B2 00

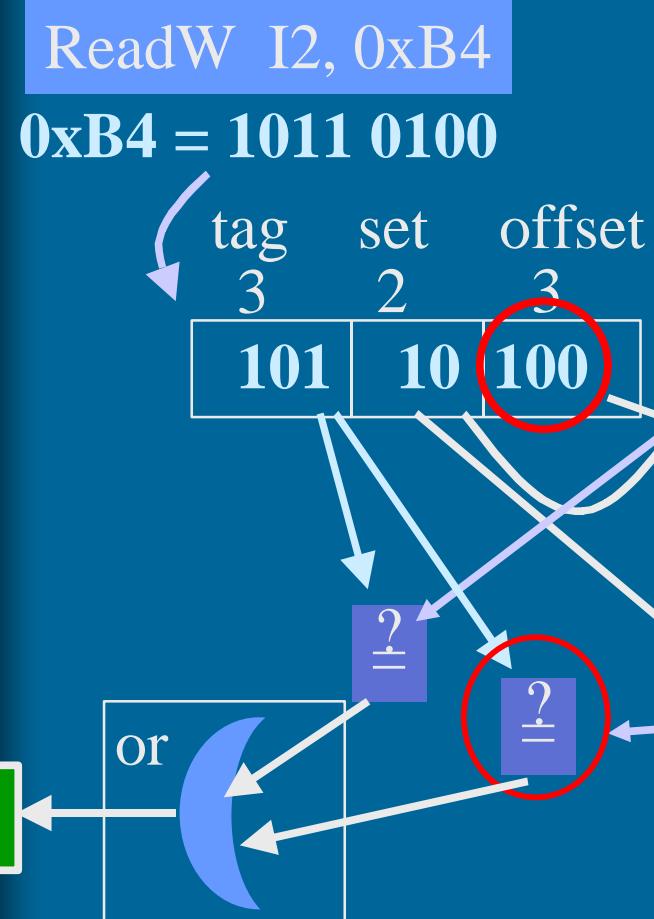
Set Associative Mapping (6)

(joukkoassosiatiivinen kuvaus)

- With set size $k=2$, every block has 2 possible locations (cache line number) in cache
 - location in each set determined by *set (index)* field bits

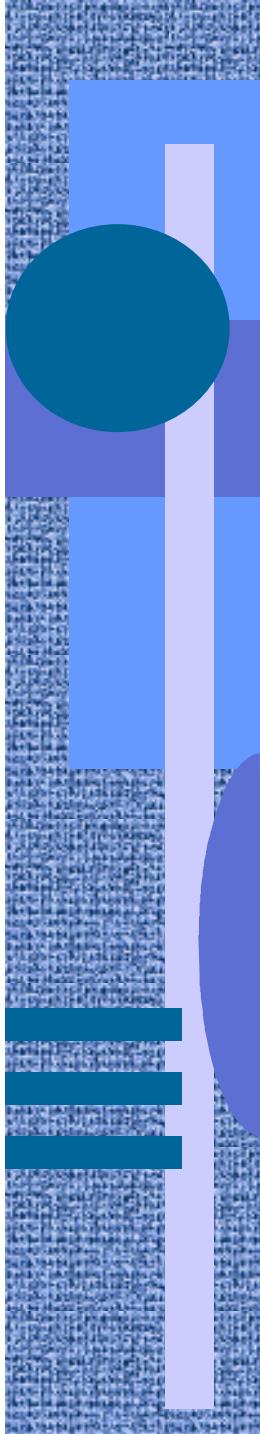


Set Associative Example (6)



cache

	tag	data	Set 0
00:	110	12 34 56 78 9A 01 23 45	
01:	110	87 00 32 89 65 A1 B2 00	
10:	100	87 54 00 89 65 A1 B2 00	
11:	101	54 A7 00 91 23 66 32 11	
00:	011	77 55 55 66 66 22 44 22	
01:	101	65 43 21 98 76 65 43 32	
10:	101	00 11 22 33 44 55 66 77	
11:	111	87 54 32 89 65 A1 B2 00	
			Set 1
00:	011	77 55 55 66 66 22 44 22	
01:	101	65 43 21 98 76 65 43 32	
10:	101	00 11 22 33 44 55 66 77	
11:	111	87 54 32 89 65 A1 B2 00	



Set Associative Mapping

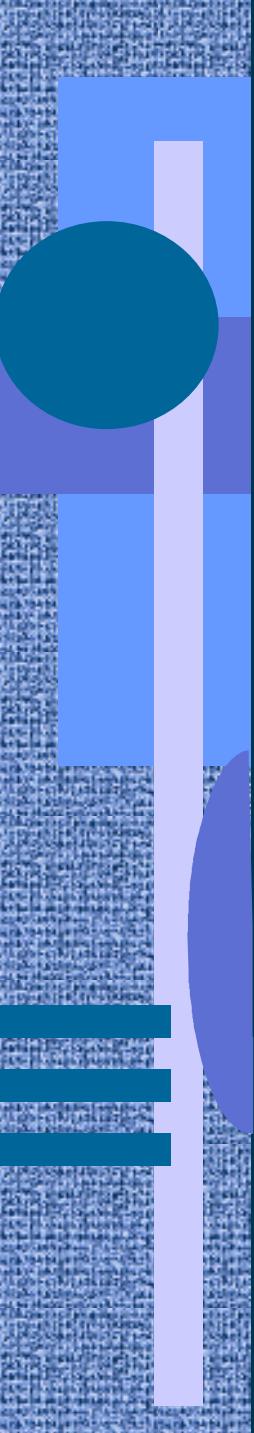
- Set associative cache with 2 sets
= 2-way cache
- Degree of associativity v ? Usually 2
 - v large?
 - More data items (v) in one set
 - less “collisions”
 - final comparison (matching tags?) gate delay?
 - v maximum (nr of cache lines)
 \Rightarrow fully associative mapping
 - v minimum (1) \Rightarrow direct mapping

Fig. 7.16 from [PaHe98]



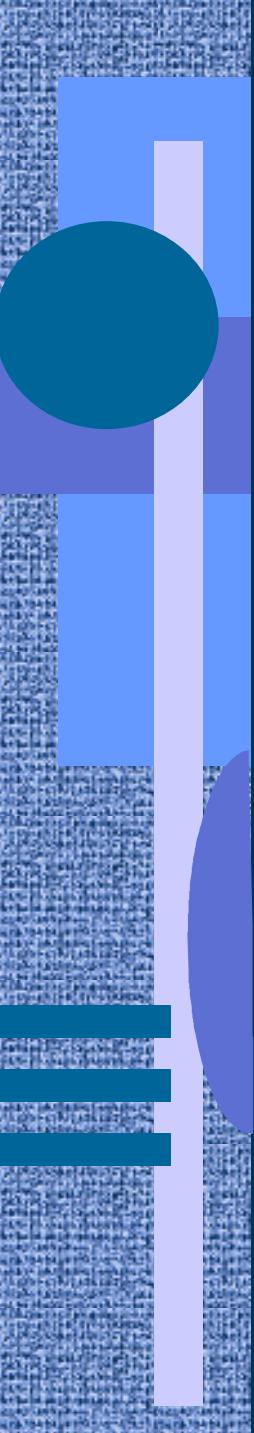
Replacement Algorithm

- Which cache line to remove to make room for new block from memory?
- Direct mapping case trivial
- First-In-First-Out (FIFO)
- Least-Frequently-Used (LFU)
- Random
- Which one is best?
 - Chip area?
 - Fast? Easy to implement?



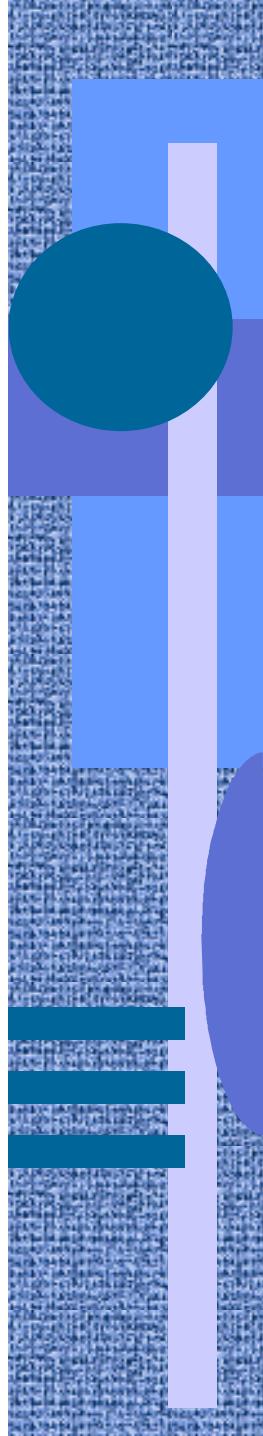
Write Policy

- How to handle writes to memory?
 - Write through
 - each write goes always to memory
 - each write is a cache miss!
 - Write back
 - write cache block to memory only when it is replaced in cache
 - memory may have stale (old) data
 - cache coherence problem
- (läpikirjoittava
lopuksi kirjoittava
takaisin kirjoittava?)
- (välimuistin
yhteneväisyyssongelma)



Line size

- How big cache line?
- Optimise for temporal or spatial locality?
- Data references and code references behave in a different way
- Best size varies with program or program phase
- 2-8 words?
 - word = 1 float??

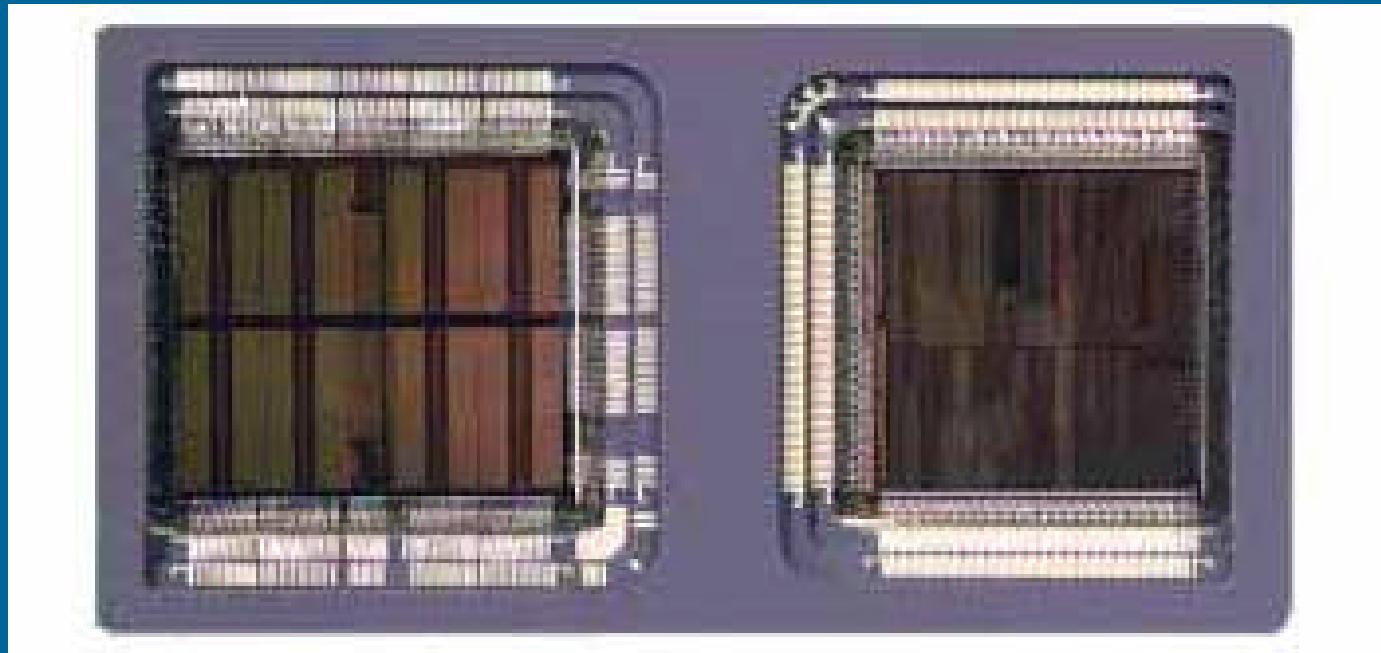


Number of Caches (3)

- One cache too large for best results
- Unified vs. split cache (yhdistetty, erilliset)
 - same cache for data and code, or not?
 - split cache: can optimise structure separately for data and code
- Multiple levels of caches
 - L1 - same chip as CPU
 - L2 - same package or chip as CPU
 - L3 - same board as CPU

Fig. 4.23

-- End of Ch. 4.3: Cache Memory --



<http://www.intel.com/procs/servers/feature/cache/unique.htm>

“The Pentium® Pro processor's unique multi-cavity chip package brings L2 cache memory closer to the CPU, delivering higher performance for business-critical computing needs.“